

Equalities and inequalities for Hermitian solutions and Hermitian definite solutions of the two matrix equations $AX = B$ and $AXA^* = B$

YONGGE TIAN

Abstract. This paper studies algebraic properties of Hermitian solutions and Hermitian definite solutions of the two types of matrix equation $AX = B$ and $AXA^* = B$. We first establish a variety of rank and inertia formulas for calculating the maximal and minimal ranks and inertias of Hermitian solutions and Hermitian definite solutions of the matrix equations $AX = B$ and $AXA^* = B$, and then use them to characterize many qualities and inequalities for Hermitian solutions and Hermitian definite solutions of the two matrix equations and their variations.

Mathematics Subject Classifications. 15A03, 15A09, 15A24, 15B57.

Keywords. Matrix equation, Hermitian solution, Hermitian definite solution, generalized inverse, rank, inertia, matrix equality, matrix inequality, Löwner partial ordering.

1 Introduction

Consider the following two well-known linear matrix equations

$$AX = B \quad (1.1)$$

and

$$AXA^* = B, \quad (1.2)$$

both of which are simplest cases of various types of linear matrix equation (with symmetric patterns), and are the starting point of many advanced study on complicated matrix equations. A huge amount of results about the two equations and applications were given in the literature. In particular, many problems on algebraic properties of solutions of the two matrix equations were explicitly characterized by using formulas for ranks and inertias of matrices. In this paper, the author focuses on Hermitian solutions or Hermitian definite solutions of (1.1) and (1.2), and studies the following optimization problems on the ranks and inertias of Hermitian solutions and Hermitian definite solutions of (1.1) and (1.2):

Problem 1.1 Let $A, B \in \mathbb{C}^{m \times n}$ be given, and assume that (1.1) has a Hermitian solution or Hermitian definite solution $X \in \mathbb{C}^{n \times n}$. In this case, establish formulas for calculating the extremal ranks and inertias of

$$X - P, \quad (1.3)$$

where $P \in \mathbb{C}^{n \times n}$ is a given Hermitian matrix, and use the formulas to characterize behaviors of these Hermitian solution and definite solution, in particular, to give necessary and sufficient conditions for the four inequalities

$$X \succ P, \quad X \succcurlyeq P, \quad X \prec P, \quad X \preccurlyeq P \quad (1.4)$$

in the Löwner partial ordering to hold, respectively.

Problem 1.2 Let $A, B, C, D \in \mathbb{C}^{m \times n}$ be given, $X, Y \in \mathbb{C}^{n \times n}$ be two unknown matrices, and assume that the two linear matrix equations

$$AX = B, \quad CY = D \quad (1.5)$$

have Hermitian solutions, respectively. In this case, establish formulas for calculating the extremal ranks and inertias of the difference

$$X - Y \quad (1.6)$$

This work was supported partially by National Natural Science Foundation of China (Grant No. 11271384).

of the Hermitian solutions, and use the formulas to derive necessary and sufficient conditions for

$$X \succ Y, \quad X \succcurlyeq Y, \quad X \prec Y, \quad X \preccurlyeq Y \quad (1.7)$$

to hold in the Löwner partial ordering, respectively.

Problem 1.3 Let $A \in \mathbb{C}^{m \times n}$ and $B \in \mathbb{C}_H^m$ be given, and assume that (1.2) has a Hermitian solution. Pre- and post-multiplying a matrix $T \in \mathbb{C}^{p \times n}$ and its conjugate transpose T^* on both sides of (1.2) yields a transformed equation as follows

$$TAXA^*T^* = TBT^*. \quad (1.8)$$

Further define

$$\mathcal{S} = \{ X \in \mathbb{C}_H^n \mid AXA^* = B \}, \quad (1.9)$$

$$\mathcal{T} = \{ Y \in \mathbb{C}_H^n \mid TAYA^*T^* = TBT^* \}. \quad (1.10)$$

In this case, give necessary and sufficient conditions for $\mathcal{S} = \mathcal{T}$ to hold, as well as necessary and sufficient conditions for $X \succ Y$, $X \succcurlyeq Y$, $X \prec Y$ and $X \preccurlyeq Y$ to hold for $X \in \mathcal{S}$ and $Y \in \mathcal{T}$, respectively.

Problem 1.4 Assume that (1.2) has a Hermitian solution, and define

$$\mathcal{S} = \{ X \in \mathbb{C}_H^n \mid AXA^* = B \}, \quad (1.11)$$

$$\mathcal{T} = \{ (X_1 + X_2)/2 \mid T_1AX_1A^*T_1^* = T_1BT_1^*, T_2AX_2A^*T_2^* = T_2BT_2^*, X_1, X_2 \in \mathbb{C}_H^n \}. \quad (1.12)$$

In this case, give necessary and sufficient conditions for $\mathcal{S} = \mathcal{T}$ to hold.

Problem 1.5 Denote the sets of all least-squares solutions and least-rank Hermitian solutions of (1.2) as

$$\mathcal{S} = \{ X \in \mathbb{C}_H^n \mid \| B - AXA^* \|_F = \min \}, \quad (1.13)$$

$$\mathcal{T} = \{ Y \in \mathbb{C}_H^n \mid r(B - AY A^*) = \min \}. \quad (1.14)$$

In this case, establish necessary and sufficient conditions for $X \succ Y$, $X \succcurlyeq Y$, $X \prec Y$ and $X \preccurlyeq Y$ to hold for $X \in \mathcal{S}$ and $Y \in \mathcal{T}$, respectively.

Matrix equations have been a prominent concerns in matrix theory and applications. As is known to all, two key tasks in solving a matrix equation is to give identifying condition for the existence of a solution of the equation, and to give general solution of the equation. Once general solution is given, the subsequent work is to describe behaviors of solutions of the matrix equation, such as, the uniqueness of solutions; the norms of solutions; the ranks and ranges of solutions, the definiteness of solutions, equalities and inequalities of solutions, etc. Problems 1.1 and 1.2 describe the inequalities for solutions of (1.1), as well as relations between solutions of two linear matrix equations.

Throughout this paper, $\mathbb{C}^{m \times n}$ and \mathbb{C}_H^m stand for the sets of all $m \times n$ complex matrices and all $m \times m$ complex Hermitian matrices, respectively; the symbols A^* , $r(A)$ and $\mathcal{R}(A)$ stand for the transpose, conjugate transpose, rank and range (column space) of a matrix $A \in \mathbb{C}^{m \times n}$, respectively; I_m denotes the identity matrix of order m ; $[A, B]$ denotes a row block matrix consisting of A and B . The Moore–Penrose inverse of a matrix $A \in \mathbb{C}^{m \times n}$, denoted by A^\dagger , is defined to be the unique matrix $X \in \mathbb{C}^{n \times m}$ satisfying the following four matrix equations

$$(i) AXA = A, \quad (ii) XAX = X, \quad (iii) (AX)^* = AX, \quad (iv) (XA)^* = XA.$$

Further, let $E_A = I_m - AA^\dagger$ and $F_A = I_n - A^\dagger A$, which ranks are given by $r(E_A) = m - r(A)$ and $r(F_A) = n - r(A)$. A well-known property of the Moore–Penrose inverse is $(A^\dagger)^* = (A^*)^\dagger$. In particular, both $(A^\dagger)^* = A^\dagger$ and $AA^\dagger = A^\dagger A$ hold if A is Hermitian, i.e., $A = A^*$. $A \succcurlyeq 0$ ($A \succ 0$) means that A is Hermitian positive semi-definite (Hermitian positive definite). Two $A, B \in \mathbb{C}_H^m$ are said to satisfy the inequality $A \succcurlyeq B$ ($A \succ B$) in the Löwner partial ordering if $A - B$ is Hermitian

positive semi-definite (Hermitian positive definite). $i_{\pm}(A)$ denotes the numbers of the positive and negative eigenvalues of a Hermitian matrix A counted with multiplicities, respectively.

The results on ranks and inertias of matrices in Lemmas 1.6 and 1.7 below are obvious or well-known (see also [10, 11] for their references), while the closed-form formulas for matrix ranks and inertias in Lemmas 1.9 and 1.12–1.15 were established by the present author, which we shall use in the latter part of this paper to derive analytical solutions to Problems 1.1–1.5.

Lemma 1.6 *Let \mathcal{S} , \mathcal{S}_1 and \mathcal{S}_2 be three sets consisting of (square) matrices over $\mathbb{C}^{m \times n}$, and let \mathcal{H} be a set consisting of Hermitian matrices over \mathbb{C}_H^m . Then, the following hold.*

- (a) *Under $m = n$, \mathcal{S} has a nonsingular matrix if and only if $\max_{X \in \mathcal{S}} r(X) = m$.*
- (b) *Under $m = n$, all $X \in \mathcal{S}$ are nonsingular if and only if $\min_{X \in \mathcal{S}} r(X) = m$.*
- (c) *$0 \in \mathcal{S}$ if and only if $\min_{X \in \mathcal{S}} r(X) = 0$.*
- (d) *$\mathcal{S} = \{0\}$ if and only if $\max_{X \in \mathcal{S}} r(X) = 0$.*
- (e) *\mathcal{H} has a matrix $X \succ 0$ ($X \prec 0$) if and only if $\max_{X \in \mathcal{H}} i_+(X) = m$ ($\max_{X \in \mathcal{H}} i_-(X) = m$).*
- (f) *All $X \in \mathcal{H}$ satisfy $X \succ 0$ ($X \prec 0$) if and only if $\min_{X \in \mathcal{H}} i_+(X) = m$ ($\min_{X \in \mathcal{H}} i_-(X) = m$).*
- (g) *\mathcal{H} has a matrix $X \succcurlyeq 0$ ($X \preccurlyeq 0$) if and only if $\min_{X \in \mathcal{H}} i_-(X) = 0$ ($\min_{X \in \mathcal{H}} i_+(X) = 0$).*
- (h) *All $X \in \mathcal{H}$ satisfy $X \succcurlyeq 0$ ($X \preccurlyeq 0$) if and only if $\max_{X \in \mathcal{H}} i_-(X) = 0$ ($\max_{X \in \mathcal{H}} i_+(X) = 0$).*
- (i) *The following hold*

$$\mathcal{S}_1 \cap \mathcal{S}_2 \neq \emptyset \Leftrightarrow \min_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} r(X_1 - X_2) = 0, \quad (1.15)$$

$$\mathcal{S}_1 \subseteq \mathcal{S}_2 \Leftrightarrow \max_{X_1 \in \mathcal{S}_1} \min_{X_2 \in \mathcal{S}_2} r(X_1 - X_2) = 0, \quad (1.16)$$

$$\mathcal{S}_1 \supseteq \mathcal{S}_2 \Leftrightarrow \max_{X_2 \in \mathcal{S}_2} \min_{X_1 \in \mathcal{S}_1} r(X_1 - X_2) = 0, \quad (1.17)$$

$$\text{there exist } X_1 \in \mathcal{S}_1 \text{ and } X_2 \in \mathcal{S}_2 \text{ such that } X_1 \succ X_2 \Leftrightarrow \max_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} i_+(X_1 - X_2) = m, \quad (1.18)$$

$$\text{there exist } X_1 \in \mathcal{S}_1 \text{ and } X_2 \in \mathcal{S}_2 \text{ such that } X_1 \succcurlyeq X_2 \Leftrightarrow \min_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} i_-(X_1 - X_2) = 0. \quad (1.19)$$

Lemma 1.7 *Let $A \in \mathbb{C}_H^m$, $B \in \mathbb{C}_H^n$, $Q \in \mathbb{C}^{m \times n}$, and assume that $P \in \mathbb{C}^{m \times m}$ is nonsingular. Then,*

$$i_{\pm}(PAP^*) = i_{\pm}(A), \quad (1.20)$$

$$i_{\pm}(\lambda A) = \begin{cases} i_{\pm}(A) & \text{if } \lambda > 0 \\ i_{\mp}(A) & \text{if } \lambda < 0 \end{cases}, \quad (1.21)$$

$$i_{\pm} \begin{bmatrix} A & 0 \\ 0 & B \end{bmatrix} = i_{\pm}(A) + i_{\pm}(B), \quad (1.22)$$

$$i_+ \begin{bmatrix} 0 & Q \\ Q^* & 0 \end{bmatrix} = i_- \begin{bmatrix} 0 & Q \\ Q^* & 0 \end{bmatrix} = r(Q). \quad (1.23)$$

Lemma 1.8 ([7]) *Let $A \in \mathbb{C}^{m \times n}$, $B \in \mathbb{C}^{m \times k}$, $C \in \mathbb{C}^{l \times n}$ and $D \in \mathbb{C}^{l \times k}$. Then,*

$$r[A, B] = r(A) + r(E_A B) = r(B) + r(E_B A), \quad (1.24)$$

$$r \begin{bmatrix} A \\ C \end{bmatrix} = r(A) + r(CF_A) = r(C) + r(AF_C), \quad (1.25)$$

$$r \begin{bmatrix} A & B \\ C & 0 \end{bmatrix} = r(B) + r(C) + r(E_B AF_C). \quad (1.26)$$

Lemma 1.9 ([10]) *Let $A \in \mathbb{C}_H^m$, $B \in \mathbb{C}^{m \times n}$, $D \in \mathbb{C}_H^n$, and let*

$$M_1 = \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix}, \quad M_2 = \begin{bmatrix} A & B \\ B^* & D \end{bmatrix}. \quad (1.27)$$

Then, the following expansion formulas hold

$$i_{\pm}(M_1) = r(B) + i_{\pm}(E_B A E_B), \quad r(M_1) = 2r(B) + r(E_B A E_B), \quad (1.28)$$

$$i_{\pm}(M_2) = i_{\pm}(A) + i_{\pm} \begin{bmatrix} 0 & E_A B \\ B^* E_A & D - B^* A^{\dagger} B \end{bmatrix}, \quad r(M_2) = r(A) + r \begin{bmatrix} 0 & E_A B \\ B^* E_A & D - B^* A^{\dagger} B \end{bmatrix}. \quad (1.29)$$

Under the condition $A \succcurlyeq 0$,

$$i_+(M_1) = r[A, B], \quad i_-(M_1) = r(B), \quad r(M_1) = r[A, B] + r(B). \quad (1.30)$$

Under the condition $\mathcal{R}(B) \subseteq \mathcal{R}(A)$,

$$i_{\pm}(M_2) = i_{\pm}(A) + i_{\pm}(D - B^* A^{\dagger} B), \quad r(M_2) = r(A) + r(D - B^* A^{\dagger} B). \quad (1.31)$$

Some general rank and inertia expansion formulas derived from (1.24)–(1.29) are given below

$$r \begin{bmatrix} A & B \\ E_P C & 0 \end{bmatrix} = r \begin{bmatrix} A & B & 0 \\ C & 0 & P \end{bmatrix} - r(P), \quad (1.32)$$

$$r \begin{bmatrix} A & B F_Q \\ C & 0 \end{bmatrix} = r \begin{bmatrix} A & B \\ C & 0 \\ 0 & Q \end{bmatrix} - r(Q), \quad (1.33)$$

$$r \begin{bmatrix} A & B F_Q \\ E_P C & 0 \end{bmatrix} = r \begin{bmatrix} A & B & 0 \\ C & 0 & P \\ 0 & Q & 0 \end{bmatrix} - r(P) - r(Q), \quad (1.34)$$

$$i_{\pm} \begin{bmatrix} A & B F_P \\ F_P B^* & 0 \end{bmatrix} = i_{\pm} \begin{bmatrix} A & B & 0 \\ B^* & 0 & P^* \\ 0 & P & 0 \end{bmatrix} - r(P), \quad (1.35)$$

$$i_{\pm} \begin{bmatrix} E_Q A E_Q & E_Q B \\ B^* E_Q & D \end{bmatrix} = i_{\pm} \begin{bmatrix} A & B & Q \\ B^* & D & 0 \\ Q^* & 0 & 0 \end{bmatrix} - r(Q). \quad (1.36)$$

We shall use them to simplify ranks and inertias of block matrices involving Moore–Penrose inverses of matrices.

Lemma 1.10 ([2]) *Let $A, B \in \mathbb{C}^{m \times n}$ be given. Then, the following hold.*

- (a) *Eq. (1.1) has a solution $X \in \mathbb{C}_H^n$ if and only if $\mathcal{R}(B) \subseteq \mathcal{R}(A)$ and $AB^* = BA^*$. In this case, the general Hermitian solution of (1.1) can be written as*

$$X = A^{\dagger} B + (A^{\dagger} B)^* - A^{\dagger} B A^{\dagger} A + F_A U F_A, \quad (1.37)$$

where $U \in \mathbb{C}_H^n$ is arbitrary.

- (b) *The matrix equation in (1.1) has a solution $0 \preccurlyeq X \in \mathbb{C}_H^n$ if and only if $\mathcal{R}(B) \subseteq \mathcal{R}(A)$, $AB^* \succcurlyeq 0$ and $\mathcal{R}(AB^*) = \mathcal{R}(BA^*) = \mathcal{R}(B)$. In this case, the general solution $0 \preccurlyeq X \in \mathbb{C}_H^n$ of (1.1) can be written as*

$$X = B^* (AB^*)^{\dagger} B + F_A U F_A, \quad (1.38)$$

where $0 \preccurlyeq U \in \mathbb{C}_H^n$ is arbitrary.

Lemma 1.11 *Eq. (1.2) has a solution $X \in \mathbb{C}_H^n$ if and only if $\mathcal{R}(B) \subseteq \mathcal{R}(A)$, or equivalently, $AA^{\dagger} B = B$. In this case, the general Hermitian solution of $AXA^* = B$ can be written as*

$$X = A^{\dagger} B (A^{\dagger})^* + F_A U + U^* F_A, \quad (1.39)$$

where $U \in \mathbb{C}^{n \times n}$ is arbitrary.

Lemma 1.12 ([11]) *Let $A_j \in \mathbb{C}^{m_j \times n}$ and $B_j \in \mathbb{C}_H^{m_j}$ be given, $j = 1, 2$, and assume that*

$$A_1 X_1 A_1^* = B_1 \quad \text{and} \quad A_2 X_2 A_2^* = B_2 \quad (1.40)$$

are solvable for $X_1, X_2 \in \mathbb{C}_H^n$. Also define

$$\mathcal{S}_j = \{ X_j \in \mathbb{C}_H^n \mid A_j X_j A_j^* = B_j \}, \quad j = 1, 2, \quad M = \begin{bmatrix} B_1 & 0 & A_1 \\ 0 & -B_2 & A_2 \\ A_1^* & A_2^* & 0 \end{bmatrix}. \quad (1.41)$$

Then,

$$\max_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} r(X_1 - X_2) = \min \{ n, \quad r(M) + 2n - 2r(A_1) - 2r(A_2) \}, \quad (1.42)$$

$$\min_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} r(X_1 - X_2) = r(M) - 2r[A_1^*, A_2^*], \quad (1.43)$$

$$\max_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} i_{\pm}(X_1 - X_2) = i_{\pm}(M) + n - r(A_1) - r(A_2), \quad (1.44)$$

$$\min_{X_1 \in \mathcal{S}_1, X_2 \in \mathcal{S}_2} i_{\pm}(X_1 - X_2) = i_{\pm}(M) - r[A_1^*, A_2^*]. \quad (1.45)$$

Consequently, the following hold.

- (a) *There exist $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ such that $X_1 - X_2$ is nonsingular if and only if $r(M) \geq 2r(A_1) + 2r(A_2) - n$.*
- (b) *$X_1 - X_2$ is nonsingular for all $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ if and only if $r(M) = 2r[A_1^*, A_2^*] + n$.*
- (c) *There exist $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ such that $X_1 = X_2$ if and only if $\mathcal{R}(B_j) \subseteq \mathcal{R}(A_j)$ and $r(M) = 2r[A_1^*, A_2^*]$, $j = 1, 2$.*
- (d) *The rank of $X_1 - X_2$ is invariant for all $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ if and only if $r(M) = 2r[A_1^*, A_2^*] - n$ or $r(A_1) = r(A_2) = n$.*
- (e) *There exist $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ such that $X_1 \succ X_2$ ($X_1 \prec X_2$) if and only if $i_+(M) = r(A_1) + r(A_2)$ ($i_-(M) = r(A_1) + r(A_2)$).*
- (f) *$X_1 \succ X_2$ ($X_1 \prec X_2$) for all $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ if and only if $i_+(M) = r[A_1^*, A_2^*] + n$ ($i_-(M) = r[A_1^*, A_2^*] + n$).*
- (g) *There exist $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ such that $X_1 \succcurlyeq X_2$ ($X_1 \preccurlyeq X_2$) if and only if $i_-(M) = r[A_1^*, A_2^*]$ ($i_+(M) = r[A_1^*, A_2^*]$).*
- (h) *$X_1 \succcurlyeq X_2$ ($X_1 \preccurlyeq X_2$) for all $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2$ if and only if $i_-(M) = r(A_1) + r(A_2) - n$ ($i_+(M) = r(A_1) + r(A_2) - n$).*
- (i) *$i_+(X_1 - X_2)$ is invariant for all $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2 \Leftrightarrow i_-(X_1 - X_2)$ is invariant for all $X_1 \in \mathcal{S}_1$ and $X_2 \in \mathcal{S}_2 \Leftrightarrow r(A_1) = r(A_2) = n$.*

Lemma 1.13 *Let $A \in \mathbb{C}_H^m$ and $B \in \mathbb{C}^{m \times n}$ be given, and denote $M = \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix}$. Then, the following hold.*

- (a) [10, 21] *The extremal ranks and inertias of $A - BXB^*$ subject to $X \in \mathbb{C}_H^n$ are given by*

$$\max_{X \in \mathbb{C}_H^n} r(A - BXB^*) = r[A, B], \quad (1.46)$$

$$\min_{X \in \mathbb{C}_H^n} r(A - BXB^*) = 2r[A, B] - r(M), \quad (1.47)$$

$$\max_{X \in \mathbb{C}_H^n} i_{\pm}(A - BXB^*) = i_{\pm}(M), \quad (1.48)$$

$$\min_{X \in \mathbb{C}_H^n} i_{\pm}(A - BXB^*) = r[A, B] - i_{\mp}(M). \quad (1.49)$$

(b) [15] *The extremal ranks and inertias of $A \pm BXB^*$ subject to $0 \preceq X \in \mathbb{C}_H^n$ are given by*

$$\max_{0 \preceq X \in \mathbb{C}_H^n} r(A + BXB^*) = r[A, B], \quad \min_{0 \preceq X \in \mathbb{C}_H^n} r(A + BXB^*) = i_+(A) + r[A, B] - i_+(M), \quad (1.50)$$

$$\max_{0 \preceq X \in \mathbb{C}_H^n} i_+(A + BXB^*) = i_+(M), \quad \min_{0 \preceq X \in \mathbb{C}_H^n} i_+(A + BXB^*) = i_+(A), \quad (1.51)$$

$$\max_{0 \preceq X \in \mathbb{C}_H^n} i_-(A + BXB^*) = i_-(A), \quad \min_{0 \preceq X \in \mathbb{C}_H^n} i_-(A + BXB^*) = r[A, B] - i_+(M), \quad (1.52)$$

$$\max_{0 \preceq X \in \mathbb{C}_H^n} r(A - BXB^*) = r[A, B], \quad \min_{0 \preceq X \in \mathbb{C}_H^n} r(A - BXB^*) = i_-(A) + r[A, B] - i_-(M), \quad (1.53)$$

$$\max_{0 \preceq X \in \mathbb{C}_H^n} i_+(A - BXB^*) = i_+(A), \quad \min_{0 \preceq X \in \mathbb{C}_H^n} i_+(A - BXB^*) = r[A, B] - i_-(M), \quad (1.54)$$

$$\max_{0 \preceq X \in \mathbb{C}_H^n} i_-(A - BXB^*) = i_-(M), \quad \min_{0 \preceq X \in \mathbb{C}_H^n} i_-(A - BXB^*) = i_-(A). \quad (1.55)$$

Lemma 1.14 ([4, 10]) *Let $A \in \mathbb{C}_H^m$, $B \in \mathbb{C}^{m \times n}$ and $C \in \mathbb{C}^{m \times k}$ be given. Then,*

$$\max_{X \in \mathbb{C}_H^n, Y \in \mathbb{C}_H^k} r(A - BXB^* - CYC^*) = r[A, B, C], \quad (1.56)$$

$$\begin{aligned} \min_{X \in \mathbb{C}_H^n, Y \in \mathbb{C}_H^k} r(A - BXB^* - CYC^*) &= 2r[A, B, C] + r \begin{bmatrix} A & B \\ C^* & 0 \end{bmatrix} - r \begin{bmatrix} A & B & C \\ B^* & 0 & 0 \end{bmatrix} \\ &\quad - r \begin{bmatrix} A & B & C \\ C^* & 0 & 0 \end{bmatrix}, \end{aligned} \quad (1.57)$$

$$\max_{X \in \mathbb{C}_H^n, Y \in \mathbb{C}_H^k} i_{\pm}(A - BXB^* - CYC^*) = i_{\pm} \begin{bmatrix} A & B & C \\ B^* & 0 & 0 \\ C^* & 0 & 0 \end{bmatrix}, \quad (1.58)$$

$$\min_{X \in \mathbb{C}_H^n, Y \in \mathbb{C}_H^k} i_{\pm}(A - BXB^* - CYC^*) = r[A, B, C] - i_{\mp} \begin{bmatrix} A & B & C \\ B^* & 0 & 0 \\ C^* & 0 & 0 \end{bmatrix}. \quad (1.59)$$

Lemma 1.15 ([5, 11]) *Let $A \in \mathbb{C}_H^m$, $B \in \mathbb{C}^{m \times n}$ and $C \in \mathbb{C}^{p \times m}$ be given and assume that $\mathcal{R}(B) \subseteq \mathcal{R}(C^*)$. Then,*

$$\max_{X \in \mathbb{C}^{n \times p}} r[A - BXC - (BXC)^*] = \min \left\{ r[A, C^*], \quad r \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix} \right\}, \quad (1.60)$$

$$\min_{X \in \mathbb{C}^{n \times p}} r[A - BXC - (BXC)^*] = 2r[A, C^*] + r \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix} - 2r \begin{bmatrix} A & B \\ C & 0 \end{bmatrix}, \quad (1.61)$$

$$\max_{X \in \mathbb{C}^{n \times p}} i_{\pm}[A - BXC - (BXC)^*] = i_{\pm} \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix}, \quad (1.62)$$

$$\min_{X \in \mathbb{C}^{n \times p}} i_{\pm}[A - BXC - (BXC)^*] = r[A, C^*] + i_{\pm} \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix} - r \begin{bmatrix} A & B \\ C & 0 \end{bmatrix}, \quad (1.63)$$

and

$$\max_{X \in \mathbb{C}^{n \times m}} r[A - BX - (BX)^*] = \min \left\{ m, \quad r \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix} \right\}, \quad (1.64)$$

$$\min_{X \in \mathbb{C}^{n \times m}} r[A - BX - (BX)^*] = r \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix} - 2r(B), \quad (1.65)$$

$$\max_{X \in \mathbb{C}^{n \times m}} i_{\pm}[A - BX - (BX)^*] = i_{\pm} \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix}, \quad (1.66)$$

$$\min_{X \in \mathbb{C}^{n \times m}} i_{\pm}[A - BX - (BX)^*] = i_{\pm} \begin{bmatrix} A & B \\ B^* & 0 \end{bmatrix} - r(B). \quad (1.67)$$

2 Properties of Hermitian solutions and Hermitian definite solutions of $AX = B$

Some formulas for calculating the ranks and inertias of Hermitian solutions and Hermitian definite solutions of the matrix equation in (1.1) were established in [11]. In this section, we reconsider the

ranks and inertias of these solutions and give a group of complete results.

Theorem 2.1 Assume that (1.1) has a Hermitian solution, and let $P \in \mathbb{C}_H^n$. Also, define

$$\mathcal{S} = \{ X \in \mathbb{C}_H^n \mid AX = B \}. \quad (2.1)$$

Then,

$$\max_{X \in \mathcal{S}} r(X - P) = r(B - AP) - r(A) + n, \quad (2.2)$$

$$\min_{X \in \mathcal{S}} r(X - P) = 2r(B - AP) - r(BA^* - APA^*), \quad (2.3)$$

$$\max_{X \in \mathcal{S}} i_{\pm}(X - P) = i_{\pm}(BA^* - APA^*) - r(A) + n, \quad (2.4)$$

$$\min_{X \in \mathcal{S}} i_{\pm}(X - P) = r(B - AP) - i_{\mp}(BA^* - APA^*). \quad (2.5)$$

In consequence, the following hold.

- (a) There exists an $X \in \mathcal{S}$ such that $X - P$ is nonsingular if and only if $\mathcal{R}(AP - B) = \mathcal{R}(A)$.
- (b) $X - P$ is nonsingular for all $X \in \mathcal{S}$ if and only if $2r(B - AP) = r(BA^* - APA^*) + n$.
- (c) There exists an $X \in \mathcal{S}$ such that $X \succ P$ ($X \prec P$) if and only if

$$\begin{aligned} \mathcal{R}(BA^* - APA^*) &= \mathcal{R}(A) \text{ and } BA^* \succcurlyeq APA^* \\ (\mathcal{R}(BA^* - APA^*) &= \mathcal{R}(A) \text{ and } BA^* \preccurlyeq APA^*). \end{aligned}$$

- (d) $X \succ P$ ($X \prec P$) holds for all $X \in \mathcal{S}$ if and only if

$$r(B - AP) = n \text{ and } BA^* \succcurlyeq APA^* \quad (r(B - AP) = n \text{ and } BA^* \preccurlyeq APA^*).$$

- (e) There exists an $X \in \mathcal{S}$ such that $X \succcurlyeq P$ ($X \preccurlyeq P$) if and only if

$$\begin{aligned} \mathcal{R}(B - AP) &= \mathcal{R}(BA^* - APA^*) \text{ and } BA^* \succcurlyeq APA^* \\ (\mathcal{R}(B - AP) &= \mathcal{R}(BA^* - APA^*) \text{ and } BA^* \preccurlyeq APA^*). \end{aligned}$$

- (f) $X \succcurlyeq P$ ($X \preccurlyeq P$) holds for all $X \in \mathcal{S}$ if and only if

$$BA^* \succcurlyeq APA^* \text{ and } r(A) = n \quad (BA^* \preccurlyeq APA^* \text{ and } r(A) = n).$$

In particular, the following hold.

- (g) There exists an $X \in \mathcal{S}$ such that X is nonsingular if and only if $\mathcal{R}(B) = \mathcal{R}(A)$.
- (h) X is nonsingular for all $X \in \mathcal{S}$ if and only if $r(B) = n$.
- (i) There exists an $X \in \mathcal{S}$ such that $X \succ 0$ ($X \prec 0$) if and only if

$$\mathcal{R}(B) = \mathcal{R}(A) \text{ and } BA^* \succcurlyeq 0 \quad (\mathcal{R}(B) = \mathcal{R}(A) \text{ and } BA^* \preccurlyeq 0).$$

- (j) $X \succ 0$ ($X \prec 0$) holds for all $X \in \mathcal{S}$ if and only if

$$r(B) = n \text{ and } BA^* \succcurlyeq 0 \quad (r(B) = n \text{ and } BA^* \preccurlyeq 0).$$

- (k) There exists an $X \in \mathcal{S}$ such that $X \succcurlyeq 0$ ($X \preccurlyeq 0$) if and only if

$$\mathcal{R}(B) = \mathcal{R}(BA^*) \text{ and } BA^* \succcurlyeq 0 \quad (\mathcal{R}(B) = \mathcal{R}(BA^*) \text{ and } BA^* \preccurlyeq 0).$$

- (l) $X \succcurlyeq 0$ ($X \preccurlyeq 0$) holds for all $X \in \mathcal{S}$ if and only if

$$BA^* \succcurlyeq 0 \text{ and } r(A) = n \quad (BA^* \preccurlyeq 0 \text{ and } r(A) = n).$$

Proof By Lemma 1.10(a), $X - P$ can be written as

$$X - P = X_0 - P + F_A U F_A, \quad (2.6)$$

where $X_0 = A^\dagger B + (A^\dagger B)^* - A^\dagger B A^\dagger A$ and $U \in \mathbb{C}_H^n$ is arbitrary. Applying Lemma 1.13(a) to (2.6) gives

$$\max_{X \in \mathcal{S}} r(X - P) = \max_{U \in \mathbb{C}_H^n} r(X_0 - P + F_A U F_A) = r[X_0 - P, F_A], \quad (2.7)$$

$$\min_{X \in \mathcal{S}} r(X - P) = \min_{U \in \mathbb{C}_H^n} r(X_0 - P + F_A U F_A) = 2r[X_0 - P, F_A] - r \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix}, \quad (2.8)$$

$$\max_{X \in \mathcal{S}} i_\pm(X - P) = \min_{U \in \mathbb{C}_H^n} i_\pm(X_0 - P + F_A U F_A) = i_\pm \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix}, \quad (2.9)$$

$$\min_{X \in \mathcal{S}} i_\pm(X - P) = \min_{U \in \mathbb{C}_H^n} i_\pm(X_0 - P + F_A U F_A) = r[X_0 - P, F_A] - i_\mp \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix}. \quad (2.10)$$

Applying (1.24) and (1.28) to the block matrices in (2.7)–(2.10) and simplifying by (1.20) and elementary block matrix operations, we obtain

$$r[X_0 - P, F_A] = r(A^\dagger A X_0 - A^\dagger A P) + r(F_A) = r(B - AP) + n - r(A), \quad (2.11)$$

$$i_\pm \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix} = r(F_A) + i_\pm[A^\dagger A(X_0 - P)A^\dagger A] = n - r(A) + i_\pm(BA^* - APA^*), \quad (2.12)$$

$$r \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix} = 2r(F_A) + r[A^\dagger A(X_0 - P)A^\dagger A] = 2n - 2r(A) + r(BA^* - APA^*). \quad (2.13)$$

Substituting (2.11)–(2.13) into (2.7)–(2.10) and simplifying leads to (2.2)–(2.5). Results (a)–(l) follow from applying Lemma 1.6 to (2.2)–(2.5). \square

Theorem 2.2 Assume that (1.1) has a Hermitian solution $X \succcurlyeq 0$, and let $0 \preccurlyeq P \in \mathbb{C}_H^n$. Also, define

$$\mathcal{S} = \{0 \preccurlyeq X \in \mathbb{C}_H^n \mid AX = B\}, \quad M = \begin{bmatrix} AB^* & B \\ B^* & P \end{bmatrix}. \quad (2.14)$$

Then,

$$\max_{X \in \mathcal{S}} r(X - P) = r(B - AP) - r(A) + n, \quad (2.15)$$

$$\min_{X \in \mathcal{S}} r(X - P) = i_-(M) + r(B - AP) - i_+(BA^* - APA^*), \quad (2.16)$$

$$\max_{X \in \mathcal{S}} i_+(X - P) = i_+(BA^* - APA^*) - r(A) + n, \quad (2.17)$$

$$\min_{X \in \mathcal{S}} i_+(X - P) = i_-(M), \quad (2.18)$$

$$\max_{X \in \mathcal{S}} i_-(X - P) = i_+(M) - r(B), \quad (2.19)$$

$$\min_{X \in \mathcal{S}} i_-(X - P) = r(B - AP) - i_+(BA^* - APA^*). \quad (2.20)$$

Consequently, the following hold.

- (a) There exists an $X \in \mathcal{S}$ such that $X - P$ is nonsingular if and only if $\mathcal{R}(B - AP) = \mathcal{R}(A)$.
- (b) $X - P$ is nonsingular for all $X \in \mathcal{S}$ if and only if $i_-(M) + r(B - AP) = i_+(BA^* - APA^*) + n$.
- (c) There exists an $X \in \mathcal{S}$ such that $X \succ P$ if and only if $\mathcal{R}(BA^* - APA^*) = \mathcal{R}(A)$ and $BA^* \succcurlyeq APA^*$.
- (d) $X \succ P$ holds for all $X \in \mathcal{S}$ if and only if $i_-(M) = n$.
- (e) There exists an $X \in \mathcal{S}$ such that $X \prec P$ if and only if $i_+(M) = r(B) + n$.

- (f) $X \prec P$ holds for all $X \in \mathcal{S}$ if and only if $r(B - AP) = n$ and $BA^* \preceq APA^*$.
- (g) There exists an $X \in \mathcal{S}$ such that $X \succcurlyeq P$ if and only if $\mathcal{R}(B - AP) = \mathcal{R}(BA^* - APA^*)$ and $BA^* \succcurlyeq APA^*$.
- (h) $X \succcurlyeq P$ holds for all $X \in \mathcal{S}$ if and only if $i_+(M) = r(B)$.
- (i) There exists an $X \in \mathcal{S}$ such that $X \preceq P$ if and only if $M \succcurlyeq 0$.
- (j) $X \preceq P$ holds for all $X \in \mathcal{S}$ if and only if $i_+(BA^* - APA^*) = n - r(A)$.

In particular, the following hold.

- (k) There exists an $X \in \mathcal{S}$ such that $X - I_n$ is nonsingular if and only if $\mathcal{R}(B - A) = \mathcal{R}(A)$.
- (l) $X - I_n$ is nonsingular for all $X \in \mathcal{S}$ if and only if $i_-(BA^* - BB^*) + r(B - A) = i_+(BA^* - AA^*) + n$.
- (m) There exists an $X \in \mathcal{S}$ such that $X \succ I_n$ if and only if $\mathcal{R}(BA^* - AA^*) = \mathcal{R}(A)$ and $BA^* \succcurlyeq AA^*$.
- (n) $X \succ I_n$ holds for all $X \in \mathcal{S}$ if and only if $BA^* \prec BB^*$.
- (o) There exists an $X \in \mathcal{S}$ such that $X \prec I_n$ if and only if $\mathcal{R}(BA^* - BB^*) = \mathcal{R}(B)$ and $BA^* \succcurlyeq BB^*$.
- (p) $X \prec I_n$ holds for all $X \in \mathcal{S}$ if and only if $r(B - A) = n$ and $BA^* \preceq AA^*$.
- (q) There exists an $X \in \mathcal{S}$ such that $X \succcurlyeq I_n$ if and only if $\mathcal{R}(B - A) = \mathcal{R}(BA^* - AA^*)$ and $BA^* \succcurlyeq AA^*$.
- (r) $X \succcurlyeq I_n$ holds for all $X \in \mathcal{S}$ if and only if $r(B) = n$ and $BA^* \preceq BB^*$.
- (s) There exists an $X \in \mathcal{S}$ such that $X \preceq I_n$ if and only if $BA^* \succcurlyeq BB^*$.
- (t) $X \preceq I_n$ holds for all $X \in \mathcal{S}$ if and only if $i_+(BA^* - AA^*) = n - r(A)$.

Proof By Lemma 1.10(b), $X - P$ can be written as

$$X - P = X_0 - P + F_A U F_A, \quad (2.21)$$

where $X_0 = B^*(AB^*)^\dagger B$ and $0 \preceq U \in \mathbb{C}_H^n$ is arbitrary. Applying Lemma 1.13(b) to (2.21) gives

$$\max_{X \in \mathcal{S}} r(X - P) = \max_{0 \preceq U \in \mathbb{C}_H^n} r(X_0 - P + F_A U F_A) = r[X_0 - P, F_A], \quad (2.22)$$

$$\begin{aligned} \min_{X \in \mathcal{S}} r(X - P) &= \min_{0 \preceq U \in \mathbb{C}_H^n} r(X_0 - P + F_A U F_A) = i_+(X_0 - P) + r[X_0 - P, F_A] \\ &\quad - i_+ \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix}, \end{aligned} \quad (2.23)$$

$$\max_{X \in \mathcal{S}} i_+(X - P) = \min_{0 \preceq U \in \mathbb{C}_H^n} i_+(X_0 - P + F_A U F_A) = i_+ \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix}, \quad (2.24)$$

$$\min_{X \in \mathcal{S}} i_+(X - P) = \min_{0 \preceq U \in \mathbb{C}_H^n} i_+(X_0 - P + F_A U F_A) = i_+(X_0 - P), \quad (2.25)$$

$$\max_{X \in \mathcal{S}} i_-(X - P) = \min_{0 \preceq U \in \mathbb{C}_H^n} i_-(X_0 - P + F_A U F_A) = i_-(X_0 - P), \quad (2.26)$$

$$\min_{X \in \mathcal{S}} i_-(X - P) = \min_{0 \preceq U \in \mathbb{C}_H^n} i_\pm(X_0 - P + F_A U F_A) = r[X_0 - P, F_A] - i_+ \begin{bmatrix} X_0 - P & F_A \\ F_A & 0 \end{bmatrix}. \quad (2.27)$$

Applying (1.21) and (1.31) to $X_0 - P$ gives

$$i_\pm(X_0 - P) = i_\mp[P - B^*(AB^*)^\dagger B^*] = i_\mp \begin{bmatrix} AB^* & B^* \\ B & P \end{bmatrix} - i_\mp(AB^*) = i_\mp(M) - i_\mp(AB^*),$$

so that

$$i_+(X_0 - P) = i_-(M), \quad i_+(X_0 - P) = i_+(M) - r(B). \quad (2.28)$$

Substituting (2.11)–(2.13) and (2.28) into (2.22)–(2.27) and simplifying leads to (2.15)–(2.20). Results (a)–(t) follow from applying Lemma 1.6 to (2.15)–(2.20). \square

A general problem related to Hermitian solutions and Hermitian definite solutions of $AX = B$ is to establish formulas for calculating the extremal ranks and inertias of $P - QXQ^*$ subject to the Hermitian solutions and Hermitian definite solutions of $AX = B$. The results obtained can be used to solve optimization problems of $P - QXQ^*$ subject to $AX = B$.

3 Relations between Hermitian solutions of $AX = B$ and $CY = D$

In order to compare Hermitian solutions of matrix equations, we first establish some fundamental formulas for calculating the extremal ranks and inertias of difference of Hermitian solutions of the two matrix equations $AX = B$ and $CY = D$, and then use them to characterize relationship between the Hermitian solutions.

Theorem 3.1 *Assume that each of the matrix equations in (1.5) has a Hermitian solution, and let*

$$\mathcal{S} = \{X \in \mathbb{C}_H^n \mid AX = B\}, \quad \mathcal{T} = \{Y \in \mathbb{C}_H^n \mid CY = D\}. \quad (3.1)$$

Also denote

$$M = \begin{bmatrix} AB^* & 0 & A \\ 0 & -CD^* & C \\ A^* & C^* & 0 \end{bmatrix}, \quad N = \begin{bmatrix} A & B \\ C & D \end{bmatrix}.$$

Then,

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = n + r(N) - r(A) - r(C), \quad (3.2)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = 2r(N) + r(AD^* - BC^*) - r \begin{bmatrix} A & BA^* \\ C & DA^* \end{bmatrix} - r \begin{bmatrix} A & BC^* \\ C & DC^* \end{bmatrix}, \quad (3.3)$$

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_{\pm}(X - Y) = n + i_{\pm}(M) - r(A) - r(C), \quad (3.4)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_{\pm}(X - Y) = r(N) - i_{\mp}(M). \quad (3.5)$$

In consequence, the following hold.

- (a) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X - Y$ is nonsingular if and only if $r(N) = r(A) + r(C)$.
- (b) $X - Y$ is nonsingular for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if

$$2r(N) + r(AD^* - BC^*) = r \begin{bmatrix} A & BA^* \\ C & DA^* \end{bmatrix} + r \begin{bmatrix} A & BC^* \\ C & DC^* \end{bmatrix} + n.$$

- (c) $\mathcal{S} \cap \mathcal{T} \neq \emptyset$ if and only if $\mathcal{R} \begin{bmatrix} B \\ D \end{bmatrix} \subseteq \mathcal{R} \begin{bmatrix} A \\ C \end{bmatrix}$, $\begin{bmatrix} A \\ C \end{bmatrix} [B^*, D^*] = \begin{bmatrix} B \\ D \end{bmatrix} [A^*, C^*]$.
- (d) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$) if and only if $i_+(M) = r(A) + r(C)$ ($i_-(M) = r(A) + r(C)$).
- (e) $X \succ Y$ ($X \prec Y$) holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_-(M) = r(N) - n$ ($i_+(M) = r(N) - n$).
- (f) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succcurlyeq Y$ ($X \preccurlyeq Y$) holds if and only if $i_+(M) = r(N)$ ($i_-(M) = r(N)$).

- (g) $X \succcurlyeq Y$ ($X \preccurlyeq Y$) holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_-(M) = r(A) + r(C) - n$ ($i_+(M) = r(A) + r(C) - n$).

Proof By Lemma 1.10(a), $X - Y$ can be written as

$$X - Y = X_0 - Y_0 + F_A U F_A - F_C V F_C, \quad (3.6)$$

where $X_0 = A^\dagger B + (A^\dagger B)^* - A^\dagger B A^\dagger A$ and $Y_0 = C^\dagger D + (C^\dagger D)^* - C^\dagger D C^\dagger C$, and $U, V \in \mathbb{C}_H^n$ are arbitrary. Applying Lemma 1.14 to (3.6) gives

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = \max_{U, V} r(X_0 - Y_0 + F_A U F_A - F_C V F_C) = r[X_0 - Y_0, F_A, F_C], \quad (3.7)$$

$$\begin{aligned} \min_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) &= \min_{U, V} r(X_0 - Y_0 + F_A U F_A - F_C V F_C) \\ &= 2r[X_0 - Y_0, F_A, F_C] + r \begin{bmatrix} X_0 - Y_0 & F_A \\ F_C & 0 \end{bmatrix} - r \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_A & 0 & 0 \end{bmatrix} \\ &\quad - r \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_C & 0 & 0 \end{bmatrix}, \end{aligned} \quad (3.8)$$

$$\begin{aligned} \max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) &= \max_{U, V} i_\pm(X_0 - Y_0 + F_A U F_A - F_C V F_C) \\ &= i_\pm \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_A & 0 & 0 \\ F_C & 0 & 0 \end{bmatrix}, \end{aligned} \quad (3.9)$$

$$\begin{aligned} \min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) &= \min_{U, V} i_\pm(X_0 - Y_0 + F_A U F_A - F_C V F_C) \\ &= r[X_0 - Y_0, F_A, F_C] - i_\mp \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_A & 0 & 0 \\ F_C & 0 & 0 \end{bmatrix}. \end{aligned} \quad (3.10)$$

Applying (1.32)–(1.34) to the block matrices in (3.7)–(3.10) and simplifying by Lemma 1.7, (1.20) and elementary block matrix operations, we obtain

$$\begin{aligned} r[X_0 - Y_0, F_A, F_C] &= r \begin{bmatrix} X_0 - Y_0 & I_n & I_n \\ 0 & A & 0 \\ 0 & 0 & C \end{bmatrix} - r(A) - r(C) \\ &= r \begin{bmatrix} 0 & I_n & I_n \\ -B & A & 0 \\ D & 0 & C \end{bmatrix} - r(A) - r(C) \\ &= r \begin{bmatrix} 0 & I_n & 0 \\ -B & 0 & -A \\ D & 0 & C \end{bmatrix} - r(A) - r(C) \\ &= n + r(N) - r(A) - r(C), \end{aligned} \quad (3.11)$$

$$\begin{aligned} r \begin{bmatrix} X_0 - Y_0 & F_A \\ F_C & 0 \end{bmatrix} &= r \begin{bmatrix} X_0 - Y_0 & I_n & 0 \\ I_n & 0 & C^* \\ 0 & A & 0 \end{bmatrix} - r(A) - r(C) \\ &= r \begin{bmatrix} 0 & I_n & D^* \\ I_n & 0 & C^* \\ -B & A & 0 \end{bmatrix} - r(A) - r(C) \\ &= r \begin{bmatrix} 0 & I_n & 0 \\ I_n & 0 & 0 \\ 0 & 0 & BC^* - AD^* \end{bmatrix} - r(A) - r(C) \\ &= 2n + r(BC^* - AD^*) - r(A) - r(C), \end{aligned} \quad (3.12)$$

$$\begin{aligned}
r \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_A & 0 & 0 \end{bmatrix} &= r \begin{bmatrix} X_0 - Y_0 & I_n & I_n & 0 \\ I_n & 0 & 0 & A^* \\ 0 & A & 0 & 0 \\ 0 & 0 & C & 0 \end{bmatrix} - 2r(A) - r(C) \\
&= r \begin{bmatrix} 0 & I_n & I_n & 0 \\ I_n & 0 & 0 & A^* \\ -B & A & 0 & 0 \\ D & 0 & C & 0 \end{bmatrix} - 2r(A) - r(C) \\
&= r \begin{bmatrix} 0 & I_n & 0 & 0 \\ I_n & 0 & 0 & 0 \\ 0 & 0 & -A & BA^* \\ 0 & 0 & C & -DA^* \end{bmatrix} - 2r(A) - r(C) \\
&= 2n + r \begin{bmatrix} A & BA^* \\ C & DA^* \end{bmatrix} - 2r(A) - r(C), \tag{3.13}
\end{aligned}$$

$$r \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_C & 0 & 0 \end{bmatrix} = 2n + r \begin{bmatrix} A & BC^* \\ C & DC^* \end{bmatrix} - r(A) - 2r(C), \tag{3.14}$$

$$\begin{aligned}
i_{\pm} \begin{bmatrix} X_0 - Y_0 & F_A & F_C \\ F_A & 0 & 0 \\ F_C & 0 & 0 \end{bmatrix} &= i_{\pm} \begin{bmatrix} X_0 - Y_0 & I_n & I_n & 0 & 0 \\ I_n & 0 & 0 & A^* & 0 \\ I_n & 0 & 0 & 0 & C^* \\ 0 & A & 0 & 0 & 0 \\ 0 & 0 & C & 0 & 0 \end{bmatrix} - r(A) - r(C) \\
&= i_{\pm} \begin{bmatrix} 0 & I_n & I_n & -B^*/2 & D^*/2 \\ I_n & 0 & 0 & A^* & 0 \\ I_n & 0 & 0 & 0 & C^* \\ -B/2 & A & 0 & 0 & 0 \\ D/2 & 0 & C & 0 & 0 \end{bmatrix} - r(A) - r(C) \\
&= i_{\pm} \begin{bmatrix} 0 & I_n & 0 & 0 & 0 \\ I_n & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -A^* & C^* \\ 0 & 0 & -A & AB^* & -AD^*/2 \\ 0 & 0 & C & -DA^*/2 & 0 \end{bmatrix} - r(A) - r(C) \\
&= n + i_{\pm} \begin{bmatrix} 0 & -A^* & C^* \\ -A & AB^* & -AD^*/2 \\ C & -DA^*/2 & 0 \end{bmatrix} - r(A) - r(C) \\
&= n + i_{\pm} \begin{bmatrix} 0 & A^* & C^* \\ A & AB^* & 0 \\ C & 0 & -CD^* \end{bmatrix} - r(A) - r(C) \\
&= n + i_{\pm}(M) - r(A) - r(C). \tag{3.15}
\end{aligned}$$

Substituting (3.11)–(3.15) into (3.7)–(3.10) and simplifying leads to (3.2)–(3.5). Results (a)–(g) follow from applying Lemma 1.6 to (3.2)–(3.5). \square

A direct consequence for $AX = B$ and its perturbation equation $(A + \delta A)Y = (B + \delta B)$ is given below.

Corollary 3.2 *Assume that both $AX = B$ and its perturbation equation $(A + \delta A)Y = (B + \delta B)$ have Hermitian solutions, and let*

$$\mathcal{S} = \{X \in \mathbb{C}_{\mathbb{H}}^n \mid AX = B\}, \quad \mathcal{T} = \{Y \in \mathbb{C}_{\mathbb{H}}^n \mid (A + \delta A)Y = (B + \delta B)\}.$$

Also denote

$$M = \begin{bmatrix} AB^* & 0 & A \\ 0 & -(A + \delta A)(B + \delta B)^* & (A + \delta A) \\ A^* & (A + \delta A)^* & 0 \end{bmatrix}, \quad N = \begin{bmatrix} A & B \\ \delta A & \delta B \end{bmatrix}.$$

Then, the following hold.

(a) *There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X - Y$ is nonsingular if and only if*

$$r \begin{bmatrix} A & B \\ \delta A & \delta B \end{bmatrix} = r(A) + r(A + \delta A).$$

(b) *$X - Y$ is nonsingular for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if*

$$2r(N) + r[A(\delta B)^* - B(\delta A)^*] = r \begin{bmatrix} A & BA^* \\ \delta A & (\delta B)A^* \end{bmatrix} + r \begin{bmatrix} A & BA^* + B(\delta A)^* \\ \delta A & (\delta B)A^* + (\delta B)(\delta A)^* \end{bmatrix} + n.$$

(c) *$\mathcal{S} \cap \mathcal{T} \neq \emptyset$ if and only if $\mathcal{R} \begin{bmatrix} B \\ \delta B \end{bmatrix} \subseteq \mathcal{R} \begin{bmatrix} A \\ \delta A \end{bmatrix}$ and $A(\delta B)^* = B(\delta A)^*$.*

(d) *There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$) if and only if $i_+(M) = r(A) + r(A + \delta A)$ ($i_-(M) = r(A) + r(A + \delta A)$).*

(e) *$X \succ Y$ ($X \prec Y$) holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_-(M) = r(N) - n$ ($i_+(M) = r(N) - n$).*

(f) *There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succcurlyeq Y$ ($X \preccurlyeq Y$) if and only if $i_+(M) = r(N)$ ($i_-(M) = r(N)$).*

(g) *$X \succcurlyeq Y$ ($X \preccurlyeq Y$) holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if*

$$i_-(M) = r(A) + r(A + \delta A) - n \quad (i_+(M) = r(A) + r(A + \delta A) - n).$$

4 Equalities and inequalities for Hermitian solutions of $AXA^* = B$ and its transformed equations

The transformation matrix equation in (1.8) may reasonably occur in the investigation of (1.2) and its variations. For instance,

(a) setting $T = A^*$ in (1.8) yields $A^*AXA^*A = A^*BA$, which is the well-known normal equation of (1.2) corresponding to $\text{trace}[(B - AXA^*)(B - AXA^*)^*] = \min$;

(b) partitioning A and B in (1.2) as $A = \begin{bmatrix} A_1 \\ A_2 \end{bmatrix}$ and $B = \begin{bmatrix} B_1 & B_2 \\ B_2^* & B_3 \end{bmatrix}$, and setting $T = [I_{m_1}, 0]$ and $T = [0, I_{m_2}]$ in (1.8), respectively, we obtain two small equations $A_1XA_1^* = B_1$ and $A_2XA_2^* = B_3$;

(c) partitioning A and X in (1.2) as $A = [A_1, A_2]$ and $X = \begin{bmatrix} X_1 & X_2 \\ X_2^* & X_3 \end{bmatrix}$, and setting $T = E_{A_1}$ and $T = E_{A_2}$, respectively, we obtain two small equations $E_{A_1}A_2X_2A_2^*E_{A_1} = E_{A_1}BE_{A_1}$ and $E_{A_2}A_1X_1A_1^*E_{A_2} = E_{A_2}BE_{A_2}$, respectively;

(d) decomposing A in (1.2) as a sum $A = A_1 + A_2$ and setting $T = E_{A_1}$ and $T = E_{A_2}$, respectively, we obtain two transformed equations $E_{A_1}A_2XA_2^*E_{A_1} = E_{A_1}BE_{A_1}$ and $E_{A_2}A_1XA_1^*E_{A_2} = E_{A_2}BE_{A_2}$, respectively.

Since solutions of (1.2) and its transformed equations are not necessarily the same, it is necessary to consider relations between the solutions of (1.2) and its transformed equations.

Theorem 4.1 *Assume that (1.2) has a Hermitian solution, and let \mathcal{S} and \mathcal{T} be defined as in (1.9) and (1.10). Then, the following hold.*

(a) *$\mathcal{S} \subseteq \mathcal{T}$ always holds, namely, all Hermitian solutions of (1.2) are solutions of (1.8).*

(b) *$\mathcal{S} = \mathcal{T}$ if and only if $r(TA) = r(A)$, or equivalently, $\mathcal{R}(A^*T^*) = \mathcal{R}(A^*)$.*

Proof If X is a Hermitian solution of (1.2), then $TAXA^*T^* = TBT^*$ holds as well. Hence, we have (a). Note from (1.17) that the set inclusion $\mathcal{S} \supseteq \mathcal{T}$ is equivalent to the following max-min rank problem

$$\max_{Y \in \mathcal{T}} \min_{X \in \mathcal{S}} r(X - Y) = 0. \quad (4.1)$$

Then, applying (1.65) and simplifying by (1.29), we obtain

$$\begin{aligned} \min_{X \in \mathcal{S}} r(X - Y) &= \min_V r[A^\dagger B(A^*)^\dagger + F_A V + V^* F_A - Y] \\ &= r \begin{bmatrix} A^\dagger B(A^\dagger)^* - Y & F_A \\ F_A & 0 \end{bmatrix} - 2r(F_A) \\ &= r[A^\dagger B(A^\dagger)^* - A^\dagger A Y A^\dagger A] = r(B - A Y A^*). \end{aligned} \quad (4.2)$$

From Lemma 1.11, the general Hermitian solution of (1.8) can be written as

$$Y = (TA)^\dagger TBT^*(A^*T^*)^\dagger - F_{TA}U - U^*F_{TA}, \quad (4.3)$$

where U is arbitrary. Applying (1.60), we obtain

$$\begin{aligned} &\max_{Y \in \mathcal{T}} r(B - A Y A^*) \\ &= \max_U r[B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* + AF_{TA}U A^* + AU^*F_{TA}A^*] \\ &= \min \left\{ r[B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^*, A], \quad r \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & AF_{TA} \\ F_{TA}A^* & 0 \end{bmatrix} \right\} \\ &= \min \left\{ r(A), \quad r \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & AF_{TA} \\ F_{TA}A^* & 0 \end{bmatrix} \right\}. \end{aligned} \quad (4.4)$$

Applying (1.35) and simplifying by (1.20) and (1.23), we obtain

$$\begin{aligned} &i_\pm \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & AF_{TA} \\ F_{TA}A^* & 0 \end{bmatrix} \\ &= i_\pm \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & A & 0 \\ A^* & 0 & A^*T^* \\ 0 & TA & 0 \end{bmatrix} - r(TA) \\ &= i_\pm \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & A & -BT^* + A(TA)^\dagger TBT^* \\ A^* & 0 & 0 \\ -TB + TBT^*(A^*T^*)^\dagger A^* & 0 & 0 \end{bmatrix} - r(TA) \\ &= i_\pm \begin{bmatrix} 0 & A & 0 \\ A^* & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} - r(TA) = r(A) - r(TA), \end{aligned} \quad (4.5)$$

so that

$$r \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & AF_{TA} \\ F_{TA}A^* & 0 \end{bmatrix} = 2r(A) - 2r(TA). \quad (4.6)$$

Substituting (4.6) into (4.4), and then (4.4) into (4.2) yields

$$\max_{Y \in \mathcal{T}} \min_{X \in \mathcal{S}_1} r(X - Y) = \min\{r(A), \quad 2r(A) - 2r(TA)\}. \quad (4.7)$$

Finally, substituting (4.7) into (4.1) leads to the result in (b). \square

Theorem 4.2 Assume that (1.2) has a Hermitian solution, and let \mathcal{S} and \mathcal{T} be as given in (1.9) and (1.10). Then, the following hold.

- (a) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$) if and only if $TA = 0$. So that if (1.8) is not null equation, there don't exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$).

(b) *There always exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$).*

Proof From (1.18) and (1.19), there exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$) if and only if

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_+(X - Y) = n \quad \left(\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_-(X - Y) = n \right); \quad (4.8)$$

there exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ ($X \prec Y$) if and only if

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_-(X - Y) = 0 \quad \left(\min_{X \in \mathcal{S}_1, Y \in \mathcal{T}} i_+(X - Y) = 0 \right). \quad (4.9)$$

From (1.39) and (4.3), the difference of $X - Y$ can be written as

$$\begin{aligned} X - Y &= A^\dagger B(A^*)^\dagger - (TA)^\dagger TBT^*(A^*T^*)^\dagger + F_A V + V^* F_A + F_{TA} U + U^* F_{TA} \\ &= A^\dagger B(A^*)^\dagger - (TA)^\dagger TBT^*(A^*T^*)^\dagger + [F_A, F_{TA}] \begin{bmatrix} V \\ U \end{bmatrix} + [V^*, U^*] \begin{bmatrix} F_A \\ F_{TA} \end{bmatrix}. \end{aligned} \quad (4.10)$$

Applying (1.66) and simplifying by (1.28) and (4.5), we obtain

$$\begin{aligned} \max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) &= i_\pm \begin{bmatrix} A^\dagger B(A^*)^\dagger - (TA)^\dagger TBT^*(A^*T^*)^\dagger & F_A & F_{TA} \\ F_A & 0 & 0 \\ F_{TA} & 0 & 0 \end{bmatrix} \\ &= i_\pm \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & AF_{TA} \\ F_A A^* & 0 \end{bmatrix} + r(F_A) \\ &= r(A) - r(TA) + n - r(A) = n - r(TA). \end{aligned} \quad (4.11)$$

Substituting (4.11) into (4.8) leads to the result in (a).

Applying (1.67) and simplifying by (1.25), (1.28) and (4.5), we obtain

$$\begin{aligned} \min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) &= i_\pm \begin{bmatrix} A^\dagger B(A^*)^\dagger - (TA)^\dagger TBT^*(A^*T^*)^\dagger & F_A & F_{TA} \\ F_A & 0 & 0 \\ F_{TA} & 0 & 0 \end{bmatrix} - r[F_A, F_{TA}] \\ &= i_\pm \begin{bmatrix} B - A(TA)^\dagger TBT^*(A^*T^*)^\dagger A^* & AF_{TA} \\ F_A A^* & 0 \end{bmatrix} - r(AF_{TA}) \\ &= r(A) - r(TA) - r(A) + r(TA) = 0. \end{aligned} \quad (4.12)$$

Substituting (4.12) into (4.9) leads to the result in (b). \square

5 Average equalities for Hermitian solutions of $AXA^* = B$ and its two transformed equations

In this section, we study the relations between the two sets in (1.11) and (1.12).

Theorem 5.1 *Assume that (1.2) has a Hermitian solution, and let \mathcal{S} and \mathcal{T} be defined as in (1.11) and (1.12), in which $T_1 \in \mathbb{C}^{p_1 \times n}$ and $T_2 \in \mathbb{C}^{p_2 \times n}$. Then,*

(a) $\mathcal{S} \subseteq \mathcal{T}$ *always holds.*

(b) $\mathcal{S} = \mathcal{T}$ *if and only if*

$$r \begin{bmatrix} T_1 A \\ T_2 A \end{bmatrix} = r(T_1 A) + r(T_2 A) - r(A). \quad (5.1)$$

(c) *In particular, if $r(T_1 A) = r(T_2 A) = r(A)$, then $\mathcal{S} = \mathcal{T}$.*

Proof If X is a Hermitian solution of (1.2), then $T_1AXA^*T_1^* = T_1BT_1^*$ and $T_2AXA^*T_2^* = T_2BT_2^*$ hold as well, and

$$r \begin{bmatrix} T_1BT_1^* & 0 & T_1A \\ 0 & -T_2BT_2^* & T_2A \\ A^*T_1^* & A^*T_2^* & 0 \end{bmatrix} = 2r \begin{bmatrix} T_1A \\ T_2A \end{bmatrix}. \quad (5.2)$$

holds by Lemma 1.12(c). This fact means that any Hermitian solution X of (1.2) can be written as $X = (X + X)/2$, the average of the two Hermitian solutions of the two equations in (1.12). Hence, we have (a).

Note from (1.17) that the set inclusion $\mathcal{S} \supseteq \mathcal{T}$ is equivalent to

$$\max_{Y \in \mathcal{T}} \min_{X \in \mathcal{S}} r(X - Y) = 0. \quad (5.3)$$

Applying (1.65), we first obtain

$$\min_{X \in \mathcal{S}} r(X - Y) = \min_V r[A^\dagger B(A^*)^\dagger + F_A V + V^* F_A - Y] = r(B - AY A^*). \quad (5.4)$$

From Lemma 1.11, the general expression of the matrices of the two equations in (1.12) can be written as

$$Y = (T_1A)^\dagger T_1BT_1^* (A^*T_1^*)^\dagger / 2 + (T_2A)^\dagger T_2BT_2^* (A^*T_2^*)^\dagger / 2 - F_{T_1A}U_1 - U_1^*F_{T_1A} - F_{T_2A}U_2 - U_2^*F_{T_2A}, \quad (5.5)$$

where U_1 and U_2 are arbitrary. Then

$$\begin{aligned} B - AY A^* &= B - A(T_1A)^\dagger T_1BT_1^* (A^*T_1^*)^\dagger A^* / 2 + A(T_2A)^\dagger T_2BT_2^* (A^*T_2^*)^\dagger A^* / 2 \\ &\quad - AF_{T_1A}U_1A^* - AU_1^*F_{T_1A}A^* - AF_{T_2A}U_2A^* - AU_2^*F_{T_2A}A^* \\ &= G - [AF_{T_1A}, AF_{T_2A}] \begin{bmatrix} U_1 \\ U_2 \end{bmatrix} A^* - A[U_1^*, U_2^*] \begin{bmatrix} F_{T_1A}A^* \\ F_{T_2A}A^* \end{bmatrix}, \end{aligned} \quad (5.6)$$

where $G = B - A(T_1A)^\dagger T_1BT_1^* (A^*T_1^*)^\dagger A^* / 2 - A(T_2A)^\dagger T_2BT_2^* (A^*T_2^*)^\dagger A^* / 2$. Applying (1.60) gives

$$\begin{aligned} \max_{Y \in \mathcal{T}} r(B - AY A^*) &= \max_{U_1, U_2} r \left(G - [AF_{T_1A}, AF_{T_2A}] \begin{bmatrix} U_1 \\ U_2 \end{bmatrix} A^* - A[U_1^*, U_2^*] \begin{bmatrix} F_{T_1A}A^* \\ F_{T_2A}A^* \end{bmatrix} \right) \\ &= \min \left\{ r(A), \quad r \begin{bmatrix} G & AF_{T_1A} & AF_{T_2A} \\ F_{T_1A}A^* & 0 & 0 \\ F_{T_2A}A^* & 0 & 0 \end{bmatrix} \right\}, \end{aligned} \quad (5.7)$$

where applying (1.35) and simplifying by elementary matrix operations, we obtain

$$\begin{aligned}
& r \begin{bmatrix} G & AF_{T_1 A} & AF_{T_2 A} \\ F_{T_1 A} A^* & 0 & 0 \\ F_{T_2 A} A^* & 0 & 0 \end{bmatrix} \\
&= r \begin{bmatrix} 2B - A(T_1 A)^\dagger T_1 B T_1^* (A^* T_1^*)^\dagger A^* - A(T_2 A)^\dagger T_2 B T_2^* (A^* T_2^*)^\dagger A^* & A & A & 0 & 0 \\ A^* & 0 & 0 & A^* T_1^* & 0 \\ A^* & 0 & 0 & 0 & A^* T_2^* \\ 0 & T_1 A & 0 & 0 & 0 \\ 0 & 0 & T_2 A & 0 & 0 \end{bmatrix} \\
&\quad - 2r(T_1 A) - 2r(T_2 A) \\
&= r \begin{bmatrix} 0 & A & 0 & 0 & 0 \\ A^* & 0 & 0 & A^* T_1^* & 0 \\ A^* & 0 & 0 & 0 & A^* T_2^* \\ -2T_1 B + T_1 B T_1^* (A^* T_1^*)^\dagger A^* + T_1 A(T_2 A)^\dagger T_2 B T_2^* (A^* T_2^*)^\dagger A^* & 0 & -T_1 A & 0 & 0 \\ 0 & 0 & T_2 A & 0 & 0 \end{bmatrix} \\
&\quad - 2r(T_1 A) - 2r(T_2 A) \\
&= r \begin{bmatrix} A^* & 0 & 0 & 0 \\ 0 & 0 & -A^* T_1^* & A^* T_2^* \\ 0 & -T_1 A & 2T_1 B T_1^* - T_1 B T_1^* - T_1 A(T_2 A)^\dagger T_2 B T_2^* (A^* T_2^*)^\dagger A^* T_1^* & 0 \\ 0 & T_2 A & 0 & 0 \end{bmatrix} \\
&\quad + r(A) - 2r(T_1 A) - 2r(T_2 A) \\
&= r \begin{bmatrix} 0 & -A^* T_1^* & A^* T_2^* \\ -T_1 A & T_1 B T_1^* - T_1 A(T_2 A)^\dagger T_2 B T_2^* (A^* T_2^*)^\dagger A^* T_1^* & 0 \\ T_2 A & 0 & 0 \end{bmatrix} + 2r(A) - 2r(T_1 A) - 2r(T_2 A) \\
&= r \begin{bmatrix} 0 & -A^* T_1^* & A^* T_2^* \\ -T_1 A & T_1 B T_1^* & -T_1 A(T_2 A)^\dagger T_2 B T_2^* \end{bmatrix} + 2r(A) - 2r(T_1 A) - 2r(T_2 A) \\
&= r \begin{bmatrix} 0 & -A^* T_1^* & A^* T_2^* \\ -T_1 A & T_1 B T_1^* & 0 \\ T_2 A & 0 & -T_2 B T_2^* \end{bmatrix} + 2r(A) - 2r(T_1 A) - 2r(T_2 A) \\
&= 2r \begin{bmatrix} T_1 A \\ T_2 A \end{bmatrix} + 2r(A) - 2r(T_1 A) - 2r(T_2 A) \quad (\text{by (5.2)}). \tag{5.8}
\end{aligned}$$

Hence,

$$\max_{Y \in \mathcal{T}} r(B - AY A^*) = \min \left\{ r(A), 2r \begin{bmatrix} T_1 A \\ T_2 A \end{bmatrix} + 2r(A) - 2r(T_1 A) - 2r(T_2 A) \right\}. \tag{5.9}$$

Setting the both sides to zero leads to the equality in (5.1). Under $r(T_1 A) = r(T_2 A) = r(A)$, both sides of (5.1) reduces to $2r(A)$. Hence, (c) follows. \square

We next give some consequences of Theorem 5.1. Partitioning A and B in (1.2) as

$$\begin{bmatrix} A_1 \\ A_2 \end{bmatrix} X [A_1^*, A_2^*] = \begin{bmatrix} B_1 & B_3 \\ B_3^* & B_2 \end{bmatrix},$$

where $A_1 \in \mathbb{C}^{m_1 \times n}$, $A_2 \in \mathbb{C}^{m_2 \times n}$, $B_1 \in \mathbb{C}_H^{m_1}$, $B_2 \in \mathbb{C}_H^{m_2}$, $B_3 \in \mathbb{C}^{m_1 \times m_2}$, $m_1 + m_2 = m$, and setting $T_1 = [I_{m_1}, 0]$ and $T = [0, I_{m_2}]$ in (1.8), respectively, we obtain two small equations

$$A_1 X A_1^* = B_1 \quad \text{and} \quad A_2 X A_2^* = B_2.$$

Let

$$\mathcal{T} = \{ (X_1 + X_2)/2 \mid A_1 X_1 A_1^* = B_1, A_2 X_2 A_2^* = B_2, X_1, X_2 \in \mathbb{C}_H^n \}. \tag{5.10}$$

Applying Theorem 5.1 to (1.11) and (5.10), we obtain the following result.

Corollary 5.2 Assume that (1.2) has a solution, and let \mathcal{S} be as given in (1.11) and \mathcal{T} as in (5.10). Then, $\mathcal{S} = \mathcal{T}$ if and only if $\mathcal{R}(A_1^*) = \mathcal{R}(A_2^*)$.

Decomposing A in (1.2) as $A = A_1 + A_2$ and setting $T = E_{A_1}$ and $T = E_{A_2}$ respectively yields the following two transformed equations

$$E_{A_1} A_2 X A_2^* E_{A_1} = E_{A_1} B E_{A_1}, \quad E_{A_2} A_1 X A_1^* E_{A_2} = E_{A_2} B E_{A_2}.$$

Also let

$$\mathcal{T} = \{(X_1 + X_2)/2 \mid E_{A_2} A_1 X_1 A_1^* E_{A_2} = E_{A_2} B E_{A_2}, E_{A_1} A_2 X_2 A_2^* E_{A_1} = E_{A_1} B E_{A_1}, X_1, X_2 \in \mathbb{C}_H^n\}. \quad (5.11)$$

Corollary 5.3 Assume that (1.2) has a solution, and let \mathcal{S} and \mathcal{T} be as given in (1.11) and (5.11). Then, the following hold.

(a) $\mathcal{S} = \mathcal{T}$ if and only if

$$r \begin{bmatrix} A_1 & 0 & A_2 \\ 0 & A_2 & A_1 \end{bmatrix} = 2r[A_1, A_2] - r(A). \quad (5.12)$$

(b) Under $\mathcal{R}(A_1) \cap \mathcal{R}(A_2) = \{0\}$, $\mathcal{S} = \mathcal{T}$ if and only if $\mathcal{R}(A_1^*) = \mathcal{R}(A_2^*)$.

Proof From Theorem 5.1(b), $\mathcal{S} = \mathcal{T}$ if and only if

$$r \begin{bmatrix} E_{A_2} A_1 \\ E_{A_1} A_2 \end{bmatrix} = r(E_{A_2} A_1) + r(E_{A_1} A_2) - r(A), \quad (5.13)$$

which is equivalent to (5.12) by (1.24). \square

In addition to the average equalities of Hermitian solutions of (1.2) and its two transformed equations, it would be of interest to consider weighted average equalities for the Hermitian solutions of (1.2) and its k transformed equations

$$T_i A X_i A^* T_i^* = T_i B T_i^*, \quad i = 1, \dots, k, \quad (5.14)$$

where $T_i \in \mathbb{C}^{p_i \times n}$. As usual, define

$$\mathcal{T} = \left\{ \sum_{i=1}^k \lambda_i X_i \mid T_i A X_i A^* T_i^* = T_i B T_i^*, X_i = X_i^*, \sum_{i=1}^k \lambda_i = 1, \lambda_i > 0, i = 1, \dots, k \right\}. \quad (5.15)$$

An open problem is to establish necessary and sufficient conditions for $\mathcal{S} = \mathcal{T}$ to hold.

6 Equalities and inequalities between least-squares and least-rank Hermitian solutions of $AXA^* = B$

It is well known that the normal equation corresponding to the norm minimization problem in (1.13) is given by

$$A^* A X A^* A = A^* B A, \quad (6.1)$$

see [1], while the normal equation corresponding to the rank minimization problem in (1.14) is given by

$$E_{T_1} Y E_{T_1} = -E_{T_1} T M^\dagger T^* E_{T_1}, \quad (6.2)$$

where $M = \begin{bmatrix} B & A \\ A^* & 0 \end{bmatrix}$, $T = [0, I_n]$ and $T_1 = T F_M$; see [10]. Both (6.1) and (6.2) are transformed equations of $AXA^* = B$. Relations between solutions of the two equations were considered in [19]. In this section, we establish a group of formulas for calculating the extremal ranks and inertias of $X - Y$ for their Hermitian solutions, and use the formulas to solve Problem 1.5.

Lemma 6.1 Let $A \in \mathbb{C}^{m \times n}$ and $B \in \mathbb{C}_H^m$ be given. Then the following hold.

(a) [1] The solution of (1.13) is

$$\min_{X \in \mathbb{C}_H^n} \|B - AXA^*\|_F = \|B - AA^\dagger BAA^\dagger\|_F, \quad (6.3)$$

$$\arg \min_{X \in \mathbb{C}_H^n} \|B - AXA^*\|_F = A^\dagger B(A^\dagger)^* + F_A U + U^* F_A, \quad (6.4)$$

where $U \in \mathbb{C}^{n \times n}$ is arbitrary.

(b) [10] The solution of (1.14) is

$$\min_{Y \in \mathbb{C}_H^n} r(B - AY A^*) = 2r[A, B] - r \begin{bmatrix} B & A \\ A^* & 0 \end{bmatrix}, \quad (6.5)$$

$$\arg \min_{Y \in \mathbb{C}_H^n} r(B - AY A^*) = -TM^\dagger T^* + T_1 V + V^* T_1^*, \quad (6.6)$$

where $V \in \mathbb{C}^{(m+n) \times n}$ is arbitrary.

Theorem 6.2 Let \mathcal{S} and \mathcal{T} be as given in (1.13) and (1.14), and define

$$M = \begin{bmatrix} B & A \\ A^* & 0 \end{bmatrix}, \quad N = \begin{bmatrix} B & BA & A \\ A^* B & 0 & 0 \\ A^* & 0 & 0 \end{bmatrix}.$$

Then,

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = \min\{n, 2n + r(N) - 2r(A) - r(M)\}, \quad (6.7)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = r(N) + r(M) - 2r[A, B] - 2r(A), \quad (6.8)$$

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) = i_\mp(N) + n - r(A) - i_\mp(M), \quad (6.9)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) = i_\mp(N) + i_\pm(M) - r[A, B] - r(A) \quad (6.10)$$

hold. Under the condition $B \succcurlyeq 0$,

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = \min\{n, 2n + r[A, BA] - 3r(A)\}, \quad (6.11)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = r[A, BA] - r(A), \quad (6.12)$$

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_+(X - Y) = r[A, BA] + n - 2r(A), \quad (6.13)$$

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_-(X - Y) = n - r(A), \quad (6.14)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_+(X - Y) = r[A, BA] - r(A), \quad (6.15)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_-(X - Y) = 0. \quad (6.16)$$

In consequence, the following hold.

- (a) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X - Y$ is nonsingular if and only if $r(N) \geq 2r(A) + r(M) - n$.
- (b) $X - Y$ is nonsingular for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $r(N) + r(M) = 2r[A, B] + 2r(A) + n$.
- (c) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X = Y$ if and only if $r(N) + r(M) = 2r[A, B] + 2r(A)$.
- (d) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ if and only if $i_-(N) = i_-(M) + r(A)$.

- (e) $X \succ Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_-(N) = r(A) + r[A, B] - i_+(M) + n$.
- (f) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ if and only if $i_+(N) = r(A) + r[A, B] - i_-(M)$.
- (g) $X \succ Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_+(N) = i_+(M) + r(A) - n$.
- (h) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \prec Y$ if and only if $i_+(N) = i_+(M) + r(A)$.
- (i) $X \prec Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_+(N) = r(A) + r[A, B] - i_-(M) + n$.
- (j) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \preccurlyeq Y$ if and only if $i_-(N) = r(A) + r[A, B] - i_+(M)$.
- (k) $X \preccurlyeq Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $i_-(N) = i_-(M) + r(A) - n$.

Under the condition $B \succcurlyeq 0$, the following hold.

- (l) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X - Y$ is nonsingular if and only if $r[A, BA] \geq 3r(A) - n$.
- (m) $X - Y$ is nonsingular for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $r[A, BA] = r(A) + n$.
- (n) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X = Y$ if and only if $\mathcal{R}(BA) \subseteq \mathcal{R}(A)$.
- (o) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succ Y$ if and only if $r[A, BA] = 2r(A)$.
- (p) $X \succ Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $r[A, BA] = r(A) + n$.
- (q) There always exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \succcurlyeq Y$.
- (r) $X \succcurlyeq Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $r(A) = n$.
- (s) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \prec Y$ if and only if $A = 0$.
- (t) There exist $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ such that $X \preccurlyeq Y$ if and only if $\mathcal{R}(BA) \subseteq \mathcal{R}(A)$.
- (u) $X \preccurlyeq Y$ holds for all $X \in \mathcal{S}$ and $Y \in \mathcal{T}$ if and only if $r[A, BA] = 2r(A) - n$.

Proof Applying (1.42)–(1.45) to (6.1) and (6.2) gives

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = \left\{ n, r \begin{bmatrix} A^*BA & 0 & A^*A \\ 0 & E_{T_1}TM^\dagger T^*E_{T_1} & E_{T_1} \\ A^*A & E_{T_1} & 0 \end{bmatrix} + 2n - 2r(A) - 2r(E_{T_1}) \right\}, \quad (6.17)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} r(X - Y) = r \begin{bmatrix} A^*BA & 0 & A^*A \\ 0 & E_{T_1}TM^\dagger T^*E_{T_1} & E_{T_1} \\ A^*A & E_{T_1} & 0 \end{bmatrix} - 2r[A^*A, E_{T_1}], \quad (6.18)$$

$$\max_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) = i_\pm \begin{bmatrix} A^*BA & 0 & A^*A \\ 0 & E_{T_1}TM^\dagger T^*E_{T_1} & E_{T_1} \\ A^*A & E_{T_1} & 0 \end{bmatrix} + n - r(A) - r(E_{T_1}), \quad (6.19)$$

$$\min_{X \in \mathcal{S}, Y \in \mathcal{T}} i_\pm(X - Y) = i_\pm \begin{bmatrix} A^*BA & 0 & A^*A \\ 0 & E_{T_1}TM^\dagger T^*E_{T_1} & E_{T_1} \\ A^*A & E_{T_1} & 0 \end{bmatrix} - r[A^*A, E_{T_1}]. \quad (6.20)$$

Applying Lemma 1.8 and simplifying by elementary operations of matrices that

$$\begin{aligned} r(E_{T_1}) &= n - r(T_1) = n - r(TF_M) = n - r \begin{bmatrix} 0 & I_n \\ B & A \\ A^* & 0 \end{bmatrix} + r(M) \\ &= r(M) - r[A, B], \end{aligned} \quad (6.21)$$

$$\begin{aligned} r[A^*A, E_{T_1}] &= r(A^*AT_1) + r(E_{T_1}) = r(ATF_M) + r(M) - r[A, B] \\ &= r \begin{bmatrix} A^*AT \\ M \end{bmatrix} - r[A, B] = r \begin{bmatrix} 0 & A \\ B & A \\ A^* & 0 \end{bmatrix} - r[A, B] = r(A), \end{aligned} \quad (6.22)$$

and by Lemma 1.8 and elementary operations of matrices that

$$\begin{aligned}
& i_{\pm} \begin{bmatrix} A^*BA & 0 & A^*A \\ 0 & E_{T_1}TM^\dagger T^*E_{T_1} & E_{T_1} \\ A^*A & E_{T_1} & 0 \end{bmatrix} \\
&= i_{\pm} \begin{bmatrix} A^*BA & 0 & A^*A & 0 \\ 0 & TM^\dagger T^* & I_n & TF_M \\ A^*A & I_n & 0 & 0 \\ 0 & E_M T & 0 & 0 \end{bmatrix} - r(TF_M) \quad (\text{by (1.35)}) \\
&= i_{\pm} \begin{bmatrix} A^*BA + A^*ATM^\dagger T^*A^*A & 0 & 0 & -A^*ATE_M \\ 0 & 0 & I_n & 0 \\ 0 & I_n & 0 & 0 \\ -E_M T^*A^*A & 0 & 0 & 0 \end{bmatrix} - r \begin{bmatrix} M \\ T \end{bmatrix} + r(M) \quad (\text{by (1.20)}) \\
&= i_{\pm} \begin{bmatrix} A^*BA + A^*ATM^\dagger T^*A^*A & A^*ATE_M \\ E_M T^*A^*A & 0 \end{bmatrix} - r[A, B] + r(M) \quad (\text{by (1.22)}) \\
&= i_{\pm} \begin{bmatrix} A^*BA & A^*AT \\ T^*A^*A & -M \end{bmatrix} - r[A, B] + i_{\pm}(M) \quad (\text{by (1.28)}) \\
&= i_{\pm} \begin{bmatrix} A^*BA & 0 & A^*A \\ 0 & -B & -A \\ A^*A & -A^* & 0 \end{bmatrix} - r[A, B] + i_{\pm}(M) \\
&= i_{\pm} \begin{bmatrix} 0 & -A^*B & 0 \\ -BA & -B & -A \\ 0 & -A^* & 0 \end{bmatrix} - r[A, B] + i_{\pm}(M) \quad (\text{by (1.20)}) \\
&= i_{\mp} \begin{bmatrix} B & BA & A \\ A^*B & 0 & 0 \\ A^* & 0 & 0 \end{bmatrix} - r[A, B] + i_{\pm}(M) \quad (\text{by (1.20) and (1.21)}) \tag{6.23} \\
&= i_{\mp}(N) - r[A, B] + i_{\pm}(M). \tag{6.24}
\end{aligned}$$

Substituting (6.21)–(6.24) into (6.17)–(6.20) yields (6.7)–(6.10).

Applying (1.30) to (6.7)–(6.10) yields (6.11)–(6.17). Applying Lemma 1.6 to (6.7)–(6.10) leads to (a)–(k). Under the condition $B \succcurlyeq 0$, applying Lemma 1.6 to (6.11)–(6.17) leads to (l)–(u). \square

The positive semi-definite least-squares Hermitian solution of (1.2) is defined to an X that satisfies

$$\|B - AXA^*\|_F = \min \quad \text{s.t.} \quad X \succcurlyeq 0; \tag{6.25}$$

the positive semi-definite least-rank Hermitian solution of (1.2) is defined to be a Y that satisfies

$$r(B - AY A^*) = \min \quad \text{s.t.} \quad Y \succcurlyeq 0. \tag{6.26}$$

The normal equations corresponding to (6.25) and (6.26) are given by

$$A^*AXA^*A = A^*BA, \quad X \succcurlyeq 0, \tag{6.27}$$

$$E_{T_1}YE_{T_1} = -E_{T_1}TM^\dagger T^*E_{T_1}, \quad Y \succcurlyeq 0. \tag{6.28}$$

Under the condition $B \succcurlyeq 0$, (6.27) and (6.28) have solutions. In this case, it would be of interest to characterize the following four inequalities

$$X \succ Y \succcurlyeq 0, \quad X \succcurlyeq Y \succcurlyeq 0, \quad Y \succ X \succcurlyeq 0, \quad Y \succcurlyeq X \succcurlyeq 0. \tag{6.29}$$

As demonstrated in the previous sections, matrix ranks and inertias and their optimizations problems are one of the most productive research field in matrix theory. The present author and his collaborators paid great attention in recent years for the development of the theory on matrix ranks and inertias, and established thousands of expansion formulas for calculating ranks and inertias of matrices; see, e.g., [3, 4, 5, 6, 8, 9, 10, 11, 12, 14, 15, 16, 17, 18, 19, 20, 21, 22] for more details. In addition, many follow-up papers by other people were also published on extensions and applications of matrix rank and inertia formulas in different situations.

References

- [1] Ben-Israel, A., Greville, T.N.E.: Generalized Inverses: Theory and Applications. Second ed., Springer, New York, 2003
- [2] Khatri, C.G., Mitra, S.K.: Hermitian and nonnegative definite solutions of linear matrix equations. *SIAM J. Appl. Math.* **31**, 579–585 (1976)
- [3] Liu, Y., Tian, Y.: Extremal ranks of submatrices in an Hermitian solution to the matrix equation $AXA^* = B$ with applications. *J. Appl. Math. Comput.* **32**, 289–301 (2010)
- [4] Liu, Y., Tian, Y.: A simultaneous decomposition of a matrix triplet with applications. *Numer. Linear Algebra Appl.* **18**, 69–85 (2011)
- [5] Liu, Y., Tian, Y.: Max-min problems on the ranks and inertias of the matrix expressions $A - BXC \pm (BXC)^*$ with applications. *J. Optim. Theory Appl.* **148**, 593–622 (2011)
- [6] Liu, Y., Tian, Y., Takane, Y.: Ranks of Hermitian and skew-Hermitian solutions to the matrix equation $AXA^* = B$. *Linear Algebra Appl.* **431**, 2359–2372 (2009)
- [7] Marsaglia, G., Styan, G.P.H.: Equalities and inequalities for ranks of matrices. *Linear Multilinear Algebra* **2**, 269–292 (1974)
- [8] Tian, Y.: On additive decompositions of solutions of the matrix equation $AXB = C$. *Calcolo* **47**, 193–209 (2010)
- [9] Tian, Y.: Completing block Hermitian matrices with maximal and minimal ranks and inertias. *Electron. J. Linear Algebra* **21**, 124–141 (2010)
- [10] Tian, Y.: Equalities and inequalities for inertias of Hermitian matrices with applications. *Linear Algebra Appl.* **433**, 263–296 (2010)
- [11] Tian, Y.: Maximization and minimization of the rank and inertia of the Hermitian matrix expression $A - BX - (BX)^*$ with applications. *Linear Algebra Appl.* **434**, 2109–2139 (2011)
- [12] Tian, Y.: Expansion formulas for the inertias of Hermitian matrix polynomials and matrix pencils of orthogonal projectors. *J. Math. Anal. Appl.* **376**, 162–186 (2011)
- [13] Tian, Y.: Extremal ranks of a quadratic matrix expression with applications. *Linear Multilinear Algebra* **59**, 627–644 (2011)
- [14] Tian, Y.: Formulas for calculating the extremum ranks and inertias of a four-term quadratic matrix-valued function and their applications. *Linear Algebra Appl.* **437**, 835–859 (2012)
- [15] Tian, Y.: Solutions to 18 constrained optimization problems on the rank and inertia of the linear matrix function $A + BXB^*$. *Math. Comput. Modelling* **55**, 955–968 (2012)
- [16] Tian, Y.: On an equality and four inequalities for generalized inverses of Hermitian matrices. *Electron. J. Linear Algebra* **23**, 11–42 (2012)
- [17] Tian, Y.: On additive decomposition of the Hermitian solution of the matrix equation $AXA^* = B$. *Mediterr. J. Math.* **9**, 47–60 (2012)
- [18] Tian, Y.: Solving optimizations problems on ranks and inertias of some constrained nonlinear matrix functions via an algebraic linearization method. *Nonlinear Analysis A* **75**, 717–734 (2012)
- [19] Tian, Y.: On relations between least-squares and least-rank Hermitian solutions of the matrix equation $AXA^* = B$ and their relations. *Numer. Linear Algebra Appl.*, doi:10.1002/nla.829
- [20] Tian, Y., Li, Y.: Distributions of eigenvalues and inertias of some block Hermitian matrices consisting of orthogonal projectors. *Linear Multilinear Algebra* **60**, 1027–1069 (2012)
- [21] Tian, Y., Liu, Y.: Extremal ranks of some symmetric matrix expressions with applications. *SIAM J. Matrix Anal. Appl.* **28**, 890–905 (2006)
- [22] Tian, Y., von Rosen, D.: Solving the matrix inequality $AXB + (AXB)^* \geq C$. *Math. Inequal. Appl.* **15**, 537–548 (2012)

Yongge Tian
China Economics and Management Academy
Central University of Finance and Economics
Beijing 100081, China
e-mail: yongge.tian@gmail.com